

Section 4.3: Eigenvalues and Eigenvectors

Friday, November 10, 2023 1:23 PM

3×3 case:

example: let $A = \begin{bmatrix} -4 & 0 & 3 \\ 0 & 2 & 0 \\ -6 & 0 & 5 \end{bmatrix}$

Find all eigenspaces of A .

answer: step ①: find eigenvalues λ using $\det(A - \lambda I) = 0$

$$\det(A - \lambda I) = \begin{vmatrix} -4-\lambda & 0 & 3 \\ 0 & 2-\lambda & 0 \\ -6 & 0 & 5-\lambda \end{vmatrix}$$

$$0 = (-4-\lambda)(2-\lambda)(5-\lambda) + 18(2-\lambda)$$

$$0 = (2-\lambda) [(-4-\lambda)(5-\lambda) + 18]$$

$$0 = (2-\lambda) [-20 - \lambda + \lambda^2 + 18]$$

$$0 = (2-\lambda)(\lambda^2 - \lambda - 2)$$

$$0 = (2-\lambda)(\lambda - 2)(\lambda + 1)$$

$$\lambda = \underbrace{2, 2}_{\text{multiplicity } 2}, \underbrace{-1}_{\text{multiplicity } 1}$$

multiplicity = number of times the value occurs in the solution

step ②: find eigenvectors using $(A - \lambda I) \vec{x} = 0$

for $\lambda_1 = 2$: $(A - 2I) \vec{x} = 0$

$$\left[\begin{array}{ccc|c} -4 & 0 & 3 & 0 \\ 0 & 2-\lambda & 0 & 0 \\ -6 & 0 & 5-\lambda & 0 \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array} \right] = \left[\begin{array}{c} 0 \\ 0 \\ 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} -4 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ -6 & 0 & 3 & 0 \end{array} \right]$$

\Downarrow RREF

$$\left[\begin{array}{ccc|c} 1 & 0 & -\frac{3}{2} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad x - \frac{3}{2}z = 0$$

$\uparrow \quad \uparrow$

$y = s \quad z = t \quad \text{free variables}$

$$\left\{ \begin{array}{l} x = \frac{3}{2}t \\ y = s \\ z = t \end{array} \right. \quad \text{so that} \quad \vec{x} = s \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} \frac{3}{2} \\ 0 \\ 1 \end{bmatrix}$$

now do $\lambda_2 = -1$: solve $(A - \lambda_2 I) \vec{x} = 0$

$$\left[\begin{array}{ccc|c} -4-\lambda_2 & 0 & 3 & 0 \\ 0 & 2-\lambda_2 & 0 & 0 \\ -6 & 0 & 5-\lambda_2 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} -3 & 0 & 3 & 0 \\ 0 & 3 & 0 & 0 \\ -6 & 0 & 6 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \quad x - z = 0$$

\uparrow

$\text{let } z = t$

$$\left\{ \begin{array}{l} x = t \\ y = 0 \\ z = t \end{array} \right. \quad \text{so then} \quad \vec{x} = t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

Step ③: write out eigenspaces

$$\text{for } \lambda_1 = 2, \quad E_{\lambda_1} = \text{span} \left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \gamma_2 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\lambda_2 = -1, \quad E_{\lambda_2} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right)$$

The algebraic multiplicity of an eigenvalue is the number of times the eigenvalue is repeated as a root of

$$\det(A - \lambda I) = 0$$

example: if $\det(A - \lambda I) = (\lambda + 1)^3(\lambda - 2)(\lambda - 4)^2$

then	eigenvalue	algebraic mult
	-1	3
	2	1
	4	2

The geometric multiplicity of an eigenvalue is the dimension of E_{λ_i} (the number of vectors in the basis of the eigenspace)

- in our previous 3×3 example, we found that

$$\lambda_1 = 2, \quad E_{\lambda_1} = \text{span} \left(\begin{bmatrix} \gamma_2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ c \end{bmatrix} \right)$$

$$\text{so } \dim(E_{\lambda_1}) = 2 \quad (\text{2D space-plane})$$

so $\lambda_1 = 2$ has geometric multiplicity of 2

- the algebraic and geometric multiplicity of an eigenvalue can be different, but

$$\text{geo mult} \leq \text{algebraic mult}$$

(if geo < alg, we say that the matrix is defective)

example: Find all eigenvalues and eigenvectors for the following matrix A . Then give the algebraic and geometric multiplicities for each eigenvalue.

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}$$

answer: $\det(A - \lambda I) = 0 = \begin{vmatrix} 1-\lambda & 2 & -1 \\ 0 & 1-\lambda & 3 \\ 0 & 0 & 2-\lambda \end{vmatrix}$

$$= (1-\lambda)^2(2-\lambda)$$

$$\lambda = 1, 2$$

↑ ↑
algebraic algebraic
mult = 2 mult = 1

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so $\lambda_1 = 1$ solve $(A - \lambda_1 I) \vec{x} = 0$

$$\left[\begin{array}{ccc|c} 0 & 2 & -1 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\text{REF}} \left[\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & c \end{array} \right]$$

$y = 0$
 $z = 0$

↑
free variable let $x = t$

$$\begin{cases} x = t \\ y = 0 \\ z = 0 \end{cases}$$

and $\vec{x}_1 = t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

↑
geometric mult
of λ_1 is 1

now $\lambda_2 = 2$

$$(A - \lambda I) \vec{x} = \vec{0}$$

$$\left[\begin{array}{ccc|c} -1 & 2 & -1 & 0 \\ 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$x - 5z = 0$
 $y - 3z = 0$
let $z = t$

$$\left\{ \begin{array}{l} x = 5t \\ y = 3t \\ z = t \end{array} \right. \quad \text{and} \quad \vec{x}_2 = t \begin{bmatrix} 5 \\ 3 \\ 1 \end{bmatrix}$$

final answer:

eigenvalue	eigenvector(s)	algebraic mult	geometric mult
1	$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$	2	1
2	$\begin{bmatrix} 5 \\ 3 \\ 1 \end{bmatrix}$	1	1

for $A \vec{x} = \lambda \vec{x}$:

$$A^2 \vec{x} = A(A \vec{x}) = A(\lambda \vec{x}) = \lambda(A \vec{x}) = \lambda^2 \vec{x}$$

$$A^3 \vec{x} = A(A^2 \vec{x}) = A(\lambda^2 \vec{x}) = \lambda^2(A \vec{x}) = \lambda^3 \vec{x}$$

$$\text{and } A^N \vec{x} = \lambda^N \vec{x} \quad \text{for any } N \geq 1$$

example: given $A = \begin{bmatrix} 1 & 2 \\ -1 & 2 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$, find $A^{100} \vec{v}$.

answer: find eigenvalues and eigenvectors of A

note: we previously found that for this A ,

eigenvalue	eigenvector
$\lambda_1 = 2$	$\vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$\begin{array}{ll} \text{assume} & \text{assume} \\ \lambda_1 = 2 & \vec{x}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} \\ \lambda_2 = 3 & \vec{x}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{array}$$

and we can see that \vec{x}_1 and \vec{x}_2 are LI
so that the set $\{\vec{x}_1, \vec{x}_2\}$ forms a basis for \mathbb{R}^2

useful fact: eigenvectors obtained from distinct eigenvalues are always LI

$$\begin{bmatrix} 2 \\ 3 \end{bmatrix} = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 2 & 1 & 7 \\ 1 & 1 & 3 \end{array} \right] \xrightarrow{\text{REF}} \left[\begin{array}{cc|c} 1 & 0 & 4 \\ 0 & 1 & -1 \end{array} \right]$$

$$\vec{v} = 4\vec{x}_1 - \vec{x}_2$$

now sub into $A^{100} \vec{v}$:

$$\begin{aligned} A^{100} \vec{v} &= A^{100} (4\vec{x}_1 - \vec{x}_2) \\ &= 4A^{100} \vec{x}_1 - A^{100} \vec{x}_2 \\ &= 4\lambda_1^{100} \vec{x}_1 - \lambda_2^{100} \vec{x}_2 \\ &= 4 \cdot 2^{100} \begin{bmatrix} 2 \\ 1 \end{bmatrix} - 3^{100} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} (2^{103} - 3^{100}) \\ (2^{102} - 3^{100}) \end{bmatrix} \end{aligned}$$

single number

this matrix is 2×1

complex eigenvalues:

example: find the eigenvalues for

$$A = \begin{bmatrix} 3 & -2 \\ 4 & -1 \end{bmatrix}$$

answer: $\det(A - \lambda I) = 0$

$$\begin{vmatrix} 3-\lambda & -2 \\ 4 & -1-\lambda \end{vmatrix} = 0$$

$$(3-\lambda)(-1-\lambda) + 8 = 0$$

$$-3 + \lambda - 3\lambda + \lambda^2 + 8 = 0$$

$$\lambda^2 - 2\lambda + 5 = 0$$

$$\begin{aligned}\lambda &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \\ &= \frac{2 \pm \sqrt{4 - 20}}{2} \\ &= \frac{2 \pm \sqrt{-16}}{2} \\ &= \frac{2 \pm 4i}{2} = 1 \pm 2i\end{aligned}$$

Note: If matrix A has real entries, complex eigenvalues always occur in conjugate pairs

now let's find eigenvectors

$$\lambda_1 = 1 + 2i$$

$$A = \begin{bmatrix} 3 & -2 \\ 4 & -1 \end{bmatrix}$$

$$\text{solve } (A - \lambda I) \vec{x} = \vec{0}$$

$$\left[\begin{array}{cc|c} 2-2i & -2 & 0 \\ 4 & -2-2i & 0 \end{array} \right]$$

method #1:

$\downarrow \quad \frac{1}{2-2i} R_1$ * could multiply by $(2+2i) R_1$ instead

$$\left[\begin{array}{cc|c} 1 & \frac{-2}{2-2i} & 0 \\ 4 & -2-2i & 0 \end{array} \right]$$

but what is $\frac{-2}{2-2i}$?

$$\frac{-2}{2-2i} \left(\frac{2+2i}{2+2i} \right) = \frac{-4-4i}{4-4i^2} = \frac{-4-4i}{8} = -\frac{1}{2} - \frac{1}{2}i$$

augmented matrix is:

$$\left[\begin{array}{ccc|c} 1 & -\frac{1}{2} & -\frac{1}{2}i & 0 \\ 0 & -2 & -2i & 0 \end{array} \right]$$

$$\downarrow R_2 - 4R_1$$

$$\left[\begin{array}{ccc|c} 1 & -\frac{1}{2} & -\frac{1}{2}i & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

method #2 for finding the RREF (please use this one!)

$$\left[\begin{array}{cc|c} 2-2i & -2 & 0 \\ 4 & -2-2i & 0 \end{array} \right]$$

$$\downarrow R_1 \leftrightarrow R_2$$

$$\left[\begin{array}{cc|c} 4 & -2-2i & 0 \\ 2-2i & -2 & 0 \end{array} \right]$$

$$\downarrow \frac{1}{4}R_1$$

$$\left[\begin{array}{cc|c} 1 & -\frac{1}{2}-\frac{1}{2}i & 0 \\ 0 & 0 & 0 \end{array} \right] \quad x + (-\frac{1}{2} - \frac{1}{2}i)y = 0$$



free variable so $y=t$

If we have done this correctly, the second row of a 2×2 here will always be a multiple of first

now find the eigenvector

$$\begin{cases} x = (\frac{1}{2} + \frac{1}{2}i)t \\ y = t \end{cases}$$

$$\vec{x}_1 = t \begin{bmatrix} \frac{1}{2} + \frac{1}{2}i \\ 1 \end{bmatrix}$$

$$= t \begin{bmatrix} 1+i \\ 2 \end{bmatrix} \quad \text{if you prefer}$$

Section 4.3 : cont'd

notice we have only found

$$\lambda_1 = 1 + 2i \quad \text{has} \quad \vec{x}_1 = \begin{bmatrix} 1+i \\ 2 \end{bmatrix}$$

but we will find that the complex conjugate of λ_1 will have the complex conjugate of \vec{x}_1 as the eigenvector

$$\text{so } \lambda_2 = 1 - 2i \quad \text{has} \quad \vec{x}_2 = \begin{bmatrix} 1-i \\ 2 \end{bmatrix}$$

and if you want to be really terse, you could also write

$$\text{for } \lambda = 1 \pm 2i, \text{ then } \vec{x} = \begin{bmatrix} 1 \pm i \\ 2 \end{bmatrix}$$

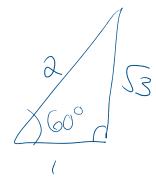
in homework, they go one step further and write

$$\vec{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \pm i \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

example : find the eigenvalues of $R(60^\circ)$

answer:

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$



$$R(60^\circ) = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$\det(A - \lambda I) = 0 = \begin{vmatrix} \frac{1}{2} - \lambda & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} - \lambda \end{vmatrix}$$

$$0 = (\frac{1}{2} - \lambda)(\frac{1}{2} - \lambda) + \frac{3}{4}$$

$$(\frac{1}{2} - \lambda)^2 = -\frac{3}{4}$$

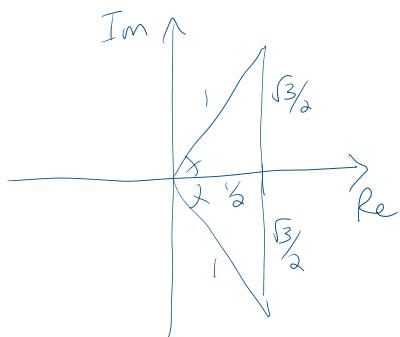
$$(\lambda - \sigma)^2 = -\frac{3}{4}$$

$$\lambda - \sigma = \pm \sqrt{-\frac{3}{4}}$$

$$\lambda = -\frac{1}{2} \pm \frac{i\sqrt{3}}{2}$$

$$\lambda = \frac{1}{2} \pm \frac{i\sqrt{3}}{2} \quad \text{or} \quad \frac{1 \pm i\sqrt{3}}{2}$$

but in the complex plane, what do these eigenvalues look like?



the angles are 60°

and the eigenvalues are

$$e^{\pm i\frac{\pi}{3}}$$

in general, the eigenvalues of R_G , the rotation matrix, are $e^{i\theta}$ and $e^{-i\theta}$