

Section 3.3: The Inverse of a Matrix

Thursday, October 13, 2022 10:07 AM

definition: the inverse of an $N \times N$ matrix A is an $N \times N$ matrix A^{-1} such that

$$AA^{-1} = I_N$$

$$A^{-1}A = I_N$$

note: matrix must be square to have an inverse

but not all square matrices have an inverse (however, if it does have an inverse, that inverse is unique)

special case: 2×2 matrices

$$\text{let } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

the determinant of A is

$$\det(A) = ad - bc$$

$$\text{then } A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

↖ swap main diagonal, other entries negate

note: A^{-1} only exists if $\det(A) \neq 0$

example: find the inverse of $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$$\text{answer: } \det(A) = ad - bc = 1(4) - 2(3) = -2$$

$$A^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$$

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check: $AA^{-1} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$

$A^{-1}A$ is similarly equal to I_2

why do we care?

suppose $AB = C$ where A , B , and C are matrices
and A and C are known -
we want to find B

long, horrible method #1:

DON'T DO THIS!

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 4 & 5 \\ 12 & 9 \end{bmatrix}$$

then

$$\left. \begin{array}{l} a + 2c = 4 \\ b + 2d = 5 \\ 3a + 4c = 12 \\ 3b + 4d = 9 \end{array} \right\} \begin{array}{l} 4 \times 4 \text{ system that} \\ \text{I need to} \\ \text{solve} \end{array}$$

YIKES!

or somewhat less annoying method #2:

$$AB = C \quad \text{where} \quad A = \begin{bmatrix} 1 & 2 \end{bmatrix}$$

$$AB = C \quad \text{where} \quad A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$C = \begin{bmatrix} 4 & 5 \\ 12 & 9 \end{bmatrix}$$

find B

answer:

$$AB = C$$

$$A^{-1}(AB) = A^{-1}C$$

$$(A^{-1}A)B = A^{-1}C$$

$$I_2 B = A^{-1}C$$

$$B = A^{-1}C$$

$$\text{now } A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad \text{so } A^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$$

$$\text{so } B = A^{-1}C$$

$$= \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix} \begin{bmatrix} 4 & 5 \\ 12 & 9 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & -1 \\ 0 & 3 \end{bmatrix}$$

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example: solve the following system using the matrix inverse

$$\begin{cases} 3x + 2y = 1 \\ 6x - y = 17 \end{cases}$$

answer: this gives the matrix equation

$$\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 17 \end{bmatrix}$$

$$A \vec{x} = \vec{b}$$

now solve for \vec{x} =

$$\begin{aligned} A \vec{x} &= \vec{b} \\ A^{-1} A \vec{x} &= A^{-1} \vec{b} \\ I \vec{x} &= A^{-1} \vec{b} \\ \vec{x} &= A^{-1} \vec{b} \end{aligned}$$

← can just write this

$$\det(A) = 3(-1) - 2(6) = -15$$

$$A^{-1} = \frac{1}{-15} \begin{bmatrix} -1 & -2 \\ -6 & 3 \end{bmatrix}$$

$$= \frac{1}{15} \begin{bmatrix} 1 & 2 \\ 6 & -3 \end{bmatrix}$$

$$\vec{x} = A^{-1} \vec{b} = \frac{1}{15} \begin{bmatrix} 1 & 2 \\ 6 & -3 \end{bmatrix} \begin{bmatrix} 1 \\ 17 \end{bmatrix}$$

$$= \frac{1}{15} \begin{bmatrix} 35 \\ -45 \end{bmatrix} = \begin{bmatrix} 7/3 \\ -3 \end{bmatrix} \text{ or } \frac{1}{3} \begin{bmatrix} 7 \\ -9 \end{bmatrix}$$

optical check: $3x + 2y = 1$

$$3(7/3) + 2(-3) = 1 \quad \checkmark$$

$$6x - y = 17$$

$$6(7/3) - (-3) = 17 \quad \checkmark$$

see handout for Properties of the Inverse of a Matrix

warning! the one we need to watch out for is

$$(AB)^{-1} = B^{-1}A^{-1}$$

my tablet died (stopped recognizing pen input) so I went to the board. Below I have copied the relevant notes from Fall 2021:

why?

$$\begin{aligned} AB(B^{-1}A^{-1}) &= A(BB^{-1})A^{-1} \\ &= AIA^{-1} \\ &= AA^{-1} \\ &= I \end{aligned}$$

$$\begin{aligned} (B^{-1}A^{-1})AB &= B^{-1}(A^{-1}A)B \\ &= B^{-1}IB \\ &= B^{-1}B \\ &= I \end{aligned}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

For matrices larger than 2×2 , we use Gauss-Jordan method to find A^{-1} :

$$[A \mid I] \xrightarrow{\text{REF}} [I \mid A^{-1}]$$

example: let $A = \begin{bmatrix} 1 & 2 & -1 \\ 3 & 7 & -5 \\ -1 & -2 & 0 \end{bmatrix}$

a) Find A^{-1} .

$$[1 \ 2 \ -1 \mid 1 \ 0 \ 0]$$

$$[1 \ 2 \ -1 \mid 1 \ 0 \ 0]$$

a) r.n.a n.

$$\left[\begin{array}{ccc|ccc} 1 & 2 & -1 & 1 & 0 & 0 \\ 3 & 7 & -5 & 0 & 1 & 0 \\ -1 & -2 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow[\substack{R_2 - 3R_1 \\ R_3 + R_1}]{\hspace{1cm}} \left[\begin{array}{ccc|ccc} 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 1 & -2 & -3 & 1 & 0 \\ 0 & 0 & -1 & 1 & 0 & 1 \end{array} \right]$$

$$\begin{array}{l} R_1 - 2R_2 \\ -R_3 \end{array} \left[\begin{array}{ccc|ccc} 1 & 0 & 3 & 7 & -2 & 0 \\ 0 & 1 & -2 & -3 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 & -1 \end{array} \right]$$

$$\begin{array}{l} R_1 - 3R_3 \\ R_2 + 2R_3 \end{array} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 10 & -2 & 3 \\ 0 & 1 & 0 & -5 & 1 & -2 \\ 0 & 0 & 1 & -1 & 0 & -1 \end{array} \right]$$

A^{-1}

check: $AA^{-1} = \begin{bmatrix} 1 & 2 & -1 \\ 3 & 7 & -5 \\ -1 & -2 & 0 \end{bmatrix} \begin{bmatrix} 10 & -2 & 3 \\ -5 & 1 & -2 \\ -1 & 0 & -1 \end{bmatrix}$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

b) Use A^{-1} to solve

$$\begin{cases} x + 2y & -z = 2 \\ 3x + 7y & -5z = 5 \\ -x - 2y & z = 1 \end{cases}$$

$$\underbrace{\begin{bmatrix} 1 & 2 & -1 \\ 3 & 7 & -5 \\ -1 & -2 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \\ z \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix}}_{\vec{b}}$$

same matrix
from part (a)

$$A\vec{x} = \vec{b}$$

$$\vec{x} = A^{-1}\vec{b}$$

$$\vec{x} = \begin{bmatrix} 10 & -2 & 3 \\ -5 & 1 & -2 \\ -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 5 \\ 1 \end{bmatrix}$$

and we note that

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{matrix} 3 \times 3 \\ 3 \times 2 \end{matrix} = \begin{bmatrix} 2 & 3 \\ 6 & 8 \\ 4 & 1 \end{bmatrix}$$

example:

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 4 & 1 & 3 \\ 2 & 1 & 0 \end{bmatrix} \xrightarrow{R_2 - 4R_1} B = \begin{bmatrix} 1 & 3 & 2 \\ 0 & -11 & -5 \\ 2 & 1 & 0 \end{bmatrix}$$

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_2 - 4R_1} E = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

and if you want, you could check that $EA = B$

recall: we only have 3 elementary row ops:

- ① $R_i \leftrightarrow R_j$
- ② cR_i where $c \neq 0$
- ③ replace R_i by $R_i + cR_j$

elementary matrices are invertible:

$$EE^{-1} = I$$

↑
undoes the elementary row op of E

examples:

$$a) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{6R_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

what is E^{-1} ?

the inverse matrix E^{-1} just undoes that row op

$$I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\frac{1}{6}R_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{6} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

totally optional check:

$$EE^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{6} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = E$

what's E^{-1} ?

$$E^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

so if we get from A to B using k elementary row operations

$$A \xrightarrow{k \text{ row ops}} B$$

then $B = E_k E_{k-1} \dots E_2 E_1 A$

↑ corresponds to the first row op

proof of Gauss-Jordan method for inverses

if $A \xrightarrow{k \text{ row ops}} I$

then $I = \underbrace{E_k E_{k-1} E_{k-2} \dots E_2 E_1}_{} A$

then $I = \underbrace{E_k E_{k-1} E_{k-2} \dots E_2 E_1}_{A^{-1}} A$

so $A^{-1} = E_k E_{k-1} E_{k-2} \dots E_2 E_1 I$

that's why $[A \mid I] \xrightarrow{k \text{ row ops}} [I \mid A^{-1}]$

example: let $A = \begin{bmatrix} 2 & 3 \\ 1 & 3 \end{bmatrix}$. Express A and A^{-1} as

a product of elementary matrices

answer:

row operations

$$[A \mid I] = \left[\begin{array}{cc|cc} 2 & 3 & 1 & 0 \\ 1 & 3 & 0 & 1 \end{array} \right]$$

$\downarrow R_1 \leftrightarrow R_2$

$$\left[\begin{array}{cc|cc} 1 & 3 & 0 & 1 \\ 2 & 3 & 1 & 0 \end{array} \right]$$

$\downarrow R_2 - 2R_1$

$$\left[\begin{array}{cc|cc} 1 & 3 & 0 & 1 \\ 0 & -3 & 1 & -2 \end{array} \right]$$

$\downarrow R_1 + R_2$

$$\left[\begin{array}{cc|cc} 1 & 0 & 1 & -1 \\ 0 & -3 & 1 & -2 \end{array} \right]$$

$\downarrow -\frac{1}{3} R_2$

$$\left[\begin{array}{cc|cc} 1 & 0 & 1 & -1 \\ 0 & 1 & -\frac{1}{3} & \frac{2}{3} \end{array} \right]$$

associated elementary matrices

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$\downarrow R_1 \leftrightarrow R_2$

$$E_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$R_2 - 2R_1$

$$E_2 = \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix}$$

$R_1 + R_2$

$$E_3 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$-\frac{1}{3} R_2$

$$E_4 = \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{3} \end{bmatrix}$$

opposite row ops (inverses)

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$\downarrow R_1 \leftrightarrow R_2$

$$E_1^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$R_2 + 2R_1$

$$E_2^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

$R_1 - R_2$

$$E_3^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$$

$-\frac{1}{3} R_2$

$$E_4^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -3 \end{bmatrix}$$

then $I = \underbrace{E_4 E_3 E_2 E_1}_{A^{-1}} A$

so $A^{-1} = E_4 E_3 E_2 E_1$

$$= \begin{bmatrix} 1 & 0 \\ 0 & -\frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -2 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{aligned} \text{and } A &= (A^{-1})^{-1} \\ &= (E_4 E_3 E_2 E_1)^{-1} \\ &= E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} \\ &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -3 \end{bmatrix} \end{aligned}$$

note: these matrices are not unique
since you could have used different row ops

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example: Find A if

$$(I_2 + 2A)^{-1} = \begin{bmatrix} 2 & 6 \\ 1 & 4 \end{bmatrix}$$

$$I_2 + 2A = \begin{bmatrix} 2 & 6 \\ 1 & 4 \end{bmatrix}^{-1}$$

$$I_2 + 2A = \frac{1}{2(4) - 6(1)} \begin{bmatrix} 4 & -6 \\ -1 & 2 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 4 & -6 \\ -1 & 2 \end{bmatrix}$$

$$2A = \frac{1}{2} \begin{bmatrix} 4 & -6 \\ -1 & 2 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -3 \\ -\frac{1}{2} & 0 \end{bmatrix}$$

$$A = \frac{1}{2} \begin{bmatrix} 1 & -3 \\ -\frac{1}{2} & 0 \end{bmatrix}$$

$$A = \frac{1}{2} \begin{bmatrix} 1 & -3 \\ -\frac{1}{2} & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{3}{2} \\ -\frac{1}{4} & 0 \end{bmatrix}$$

example: solve for X , assuming all matrices are invertible

$$(B^{-1})^2 B^2 A^2 X A^{-1} B^{-1} = I$$



$$\underbrace{B^{-2} B^2}_I A^2 X A^{-1} B^{-1} = B^{-2} I$$

$$\underbrace{A^{-2} A^2}_I X A^{-1} B^{-1} = A^{-2} B^{-2} I$$

$$X A^{-1} \underbrace{B^{-1} B}_I = A^{-2} B^{-2} B$$

$$X A^{-1} = A^{-2} B^{-1} \underbrace{B^{-1} B}_I$$

$$X A^{-1} A = A^{-2} B^{-1} A$$

$$X = A^{-2} B^{-1} A$$

optional check:

$$B^2 A^2 X A^{-1} B^{-1} = I$$

$$\underbrace{B^2 A^2 A^{-2} B^{-1} A}_I \underbrace{A^{-1} B^{-1}}_I = I$$

$$B^2 B^{-1} B^{-1} = I \quad \checkmark$$