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Instructor: Patricia Wrean

## Math 251 <br> Test 3

## Total $=\overline{20}$

Show your work. All of the work on this test must be your own.

$$
\begin{gathered}
\operatorname{proj}_{\mathbf{u}} \mathbf{v}=\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{u} \cdot \mathbf{u}} \mathbf{u} \\
R_{\theta}=\left[\begin{array}{rr}
\cos \theta & -\sin \theta \\
\sin \theta & \cos \theta
\end{array}\right]
\end{gathered}
$$

## GOOD LUCK!

1. (5 points) Consider the transformation $T$ which rotates a vector in $\mathbb{R}^{2}$ clockwise by $135^{\circ}$ and then reflects it about the line $y=-x$.
(a) Find the standard matrix $A$ for this transformation.
(b) Now evaluate $T(\mathbf{v})$ for $\mathbf{v}=\left[\begin{array}{c}3 \\ -1\end{array}\right]$.
2. (4 points) Find all values of $z$ such that $z^{6}=-64 i$.

Give exact answers. You may leave your answer in either rectangular or polar form, your choice. If using polar form, your angles should satisfy $0 \leq \theta<2 \pi$ or $0 \leq \theta<360^{\circ}$, as appropriate.
3. (2 points) Compute the determinant of the following matrix.

$$
A=\left[\begin{array}{cccc}
2 & 0 & 3 & 5 \\
-1 & -2 & 0 & 3 \\
0 & 2 & 0 & 0 \\
3 & -3 & k & 0
\end{array}\right]
$$

Your answer should be in terms of $k$.
4. (5 points) Consider the matrix $A$ given below.

$$
A=\left[\begin{array}{ll}
1 & 2 \\
4 & 3
\end{array}\right]
$$

(a) Find diagonal matrix $D$ and invertible matrix $P$ such that $A=P D P^{-1}$.
(b) Using your result for part (a), calculate $A^{6}$.
5. (4 points) Consider the set of vectors $\mathcal{B}$ below and also the vector $\mathbf{u}$. $\mathcal{B}$ is a basis of $\mathbb{R}^{3}$.

$$
\mathcal{B}=\left\{\left[\begin{array}{l}
1 \\
1 \\
0
\end{array}\right],\left[\begin{array}{c}
1 \\
-1 \\
-1
\end{array}\right],\left[\begin{array}{c}
1 \\
-1 \\
2
\end{array}\right]\right\} \quad \text { and } \quad \mathbf{u}=\left[\begin{array}{c}
-1 \\
5 \\
3
\end{array}\right]
$$

(a) Show that $\mathcal{B}$ is an orthogonal basis of $\mathbb{R}^{3}$.
(b) Using the fact that $\mathcal{B}$ is an orthogonal basis, express the vector $\mathbf{u}$ as a linear combination of the vectors in $\mathcal{B}$.

