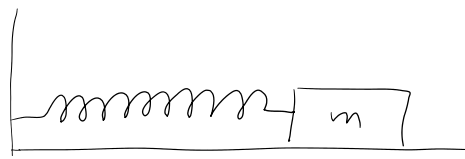


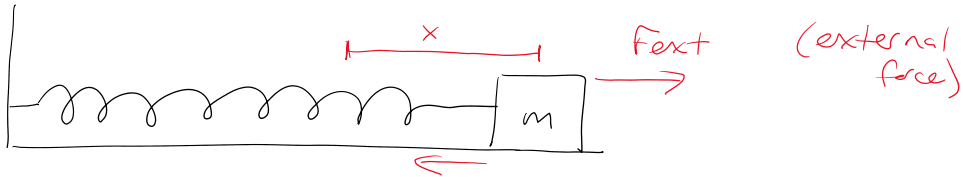
Section 5.1: Linear Models (2nd order applications)

Thursday, March 02, 2023 2:36 PM

Hooke's Law:

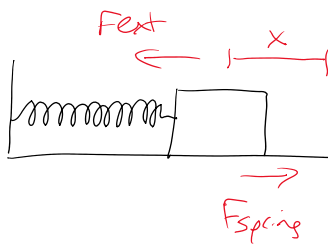


Consider mass m on a frictionless surface with an ideal spring



(external force)

F_{spring} is in opposite direction, and tries to return mass to the equilibrium position



if the external force is in the opposite direction, then

F_{spring} still opposes it and tries to return mass to the equilibrium position

we call this type of force a "restoring force"

Hooke's Law:
$$\vec{F}_{\text{spring}} = -k\vec{x}$$

↑
the displacement

now let's let go of the block so $F_{\text{ext}} = 0$

then

$$\sum \vec{F} = m\vec{a} \quad \text{Newton's 2nd Law}$$

$$\vec{F}_{\text{spring}} = m\vec{a}$$

$$-kx = m \frac{d^2x}{dt^2}$$

$$m \frac{d^2x}{dt^2} + kx = 0$$

2nd order linear DE

$$\left[\text{or } m\ddot{x} + kx = 0 \right]$$

let's solve it!

$$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0$$

aux eqn: use n 's instead since m is now mass

$$n^2 + \frac{k}{m} = 0$$

$$n^2 = -\frac{k}{m}$$

$$n = \pm i \sqrt{\frac{k}{m}}$$

$$\begin{aligned} x &= e^{\alpha t} (c_1 \cos \beta t + c_2 \sin \beta t) \\ &= c_1 \cos \left(\sqrt{\frac{k}{m}} t \right) + c_2 \sin \left(\sqrt{\frac{k}{m}} t \right) \end{aligned}$$

a common convention is to say that $\omega_0 = \sqrt{\frac{k}{m}}$
↑
lowercase omega

$\omega_0 =$ angular frequency

$$\text{so } x = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t$$

note: ω_0 is related to f_0 , the natural frequency,

by $f = \frac{\omega}{2\pi}$ and also the

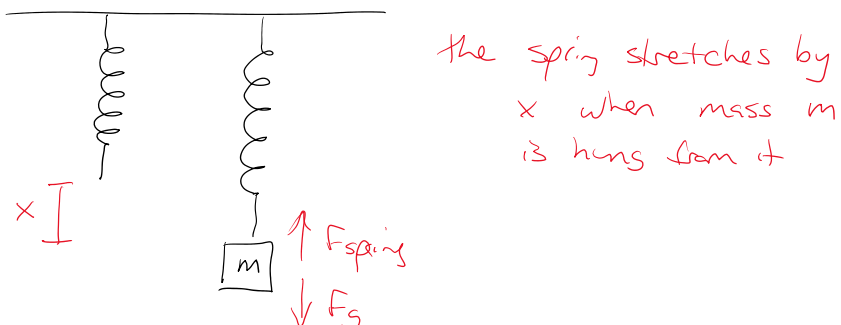
period T is given by $T = \frac{2\pi}{\omega}$

so what does this look like?

- single sine wave with a phase shift

(more details later)

so, how do you calculate k , the spring constant?



forces down = forces up (mass is in equilibrium)

$$F_g = F_{\text{spring}}$$

$$mg = kx$$

$$k = \frac{mg}{x}$$

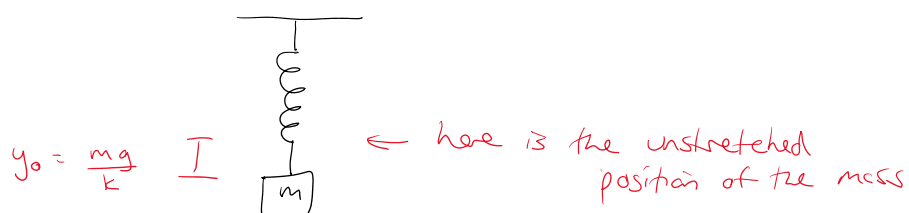
if $m = 9.0 \text{ kg}$ and $x = 3.0 \text{ m}$, then using $g = 9.8 \text{ m/s}^2 = 9.8 \text{ N/kg}$

$$\text{then } k = \frac{mg}{x} = \frac{(9.0 \text{ kg})(9.8 \text{ N/kg})}{3.0 \text{ m}}$$

$$= 29.4 \text{ N/m}$$

$$= 29 \text{ N/m}$$

note: what happens when a spring is hung vertically and then set in motion?



you get that

$$m \frac{d^2 y}{dt^2} + ky = F_{\text{ext}}$$

$$m \frac{d^2 y}{dt^2} + ky = mg$$

non homogeneous

but we can just rewrite this as

$$m \frac{d^2 y}{dt^2} + k(y - y_0) = 0$$

↑
 y_0 is the length the spring stretches when the mass is hung

and can redefine coordinates

Section 5.1: cont'd

2023/03/03

example: A 0.25 kg mass is hung from a spring with spring constant 1.0 N/m. The mass is released 0.50 m below equilibrium with velocity 2 m/s upwards. Assume no damping.

a) Find $y(t)$

$$\sum \vec{F} = m\vec{a}$$

$$-ky = m \frac{d^2 y}{dt^2}$$

$$m \frac{d^2 y}{dt^2} + ky = 0$$

$$0.25 \frac{d^2 y}{dt^2} + 1.0 y = 0$$

aux eqn: $0.25 n^2 + 1.0 = 0$

$$n^2 = \frac{-1.0}{0.25} = -4$$

note: the force of gravity stretches the spring so that it oscillates about a new equilibrium position - so don't have to include here

$$n = \pm 2i$$

$$y = e^{\alpha t} (c_1 \cos \beta t + c_2 \sin \beta t)$$

$$y = c_1 \cos 2t + c_2 \sin 2t$$

now apply initial conditions:

↑ y (positive is up)

$$y(0) = -0.50 \text{ m}$$

$$\frac{dy}{dt}(0) = 2.0 \text{ m/s}$$

note: either convention is okay but be consistent

$$\text{at } t=0, \quad -0.50 = c_1 \cancel{\cos 0} + c_2 \cancel{\sin 0}$$

$$c_1 = -0.50$$

$$\text{at } t=0, \quad \frac{dy}{dt} = 2.0$$

$$\frac{dy}{dt} = -2c_1 \sin 2t + 2c_2 \cos 2t$$

$$2 = -2c_1 \cancel{\sin 0} + 2c_2 \cancel{\cos 0}$$

$$c_2 = 1.0$$

$$y(t) = -0.50 \cos 2t + 1.0 \sin 2t$$

b) write $y(t)$ in the form of $A \sin(\omega t + \phi)$

(see handout of Linear Combo of Sine and Cosine)

$$A = \sqrt{c_1^2 + c_2^2} \quad \text{and} \quad \tan \phi = \frac{c_1}{c_2}$$

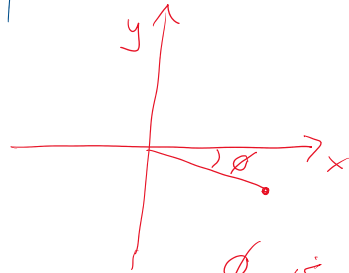
from our problem, $c_1 = -0.5$

$$c_2 = 1.0$$

$$\begin{aligned} \text{so } A &= \sqrt{(-0.5)^2 + (1.0)^2} \\ &= 1.11803 \\ &= 1.1 \end{aligned}$$

$$\tan \phi = \frac{-0.5}{1} \quad \left(= \frac{y}{x} \right)$$

$$(x, y) = (1, -0.5)$$



ϕ is in QIV

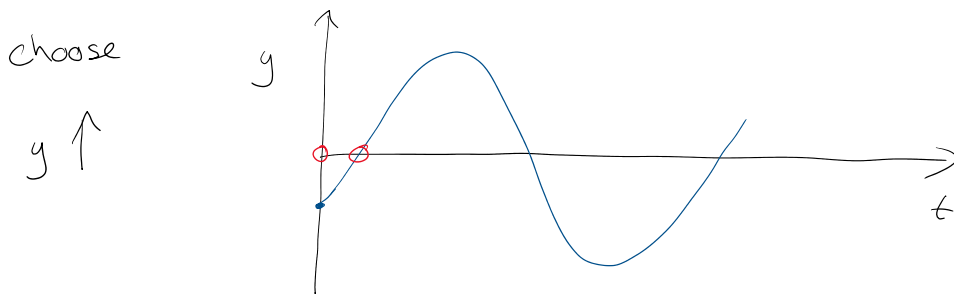
$$\begin{aligned} \text{and } \arctan \left(\frac{-0.5}{1.0} \right) &= -26.6^\circ \\ &= -0.463648 \text{ radians} \\ &= -0.46 \text{ rads} \end{aligned}$$

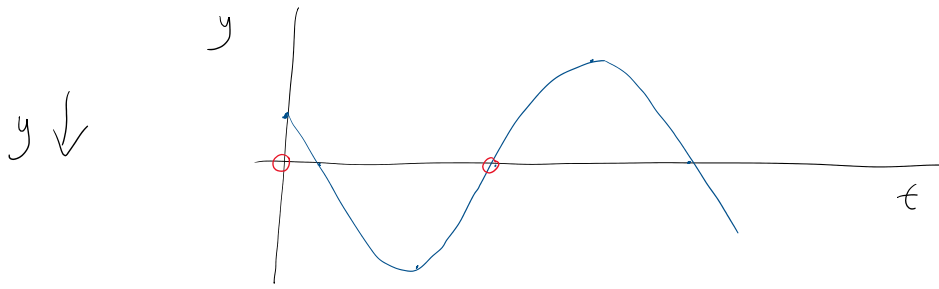
since ϕ is in QIV, then $\phi = -0.46$ rads
with no need to add π

(in QII and QIII, will need to add π to
the angle calculated from
arctan function)

$$\text{therefore, } y(t) = 1.1 \sin(2t - 0.46)$$

note: if you use $\downarrow y$ (positive is down), you
will get a different value for the phase shift





c) Find the mass's maximum displacement from equilibrium position.

$$\pm 1.1 \text{ m}$$

d) Find the period of motion.

$$\text{period} = \frac{2\pi}{\omega} = \frac{2\pi}{2} = \pi \text{ seconds/cycle}$$

e) Find the time when the mass first returns to equilibrium position

$$y = 1.1 \sin(2t - 0.46)$$

$$0 = 1.1 \sin(2t - 0.46)$$

↑
infinite number of values of t that make this true - we want the smallest positive value

$$2t - 0.46 = \dots -2\pi, -\pi, 0, \pi, 2\pi, \dots$$

$$2t - 0.46 = 0 \text{ has a positive solution}$$

$$2t = 0.46$$

$$t = 0.23 \text{ seconds}$$

section 5.1: cont'd

2023/03/07

so what happens when we consider air resistance?

$$F_{fr} \propto v$$

$$\text{so } \vec{F}_{fr} = -b\vec{v}$$

↑

b is a positive constant

and the force of friction due to air resistance is in the opposite direction to the velocity

so then $\sum \vec{F} = m\vec{a}$

$$\vec{F}_{spring} + \vec{F}_{fr} = m\vec{a}$$

$$-kx - b\dot{x} = m\ddot{x}$$

$$\begin{aligned} m\ddot{x} + b\dot{x} + kx &= 0 \\ m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx &= 0 \\ m\ddot{x} + b\dot{x} + kx &= 0 \end{aligned}$$

2nd order linear homogeneous

aux eqn: $mn^2 + bn + k = 0$

$$n = \frac{-b \pm \sqrt{b^2 - 4km}}{2m}$$

sols will be (1) 2 distinct real if $b^2 - 4km > 0$

(2) 1 repeated real if " = 0

③ 2 complex

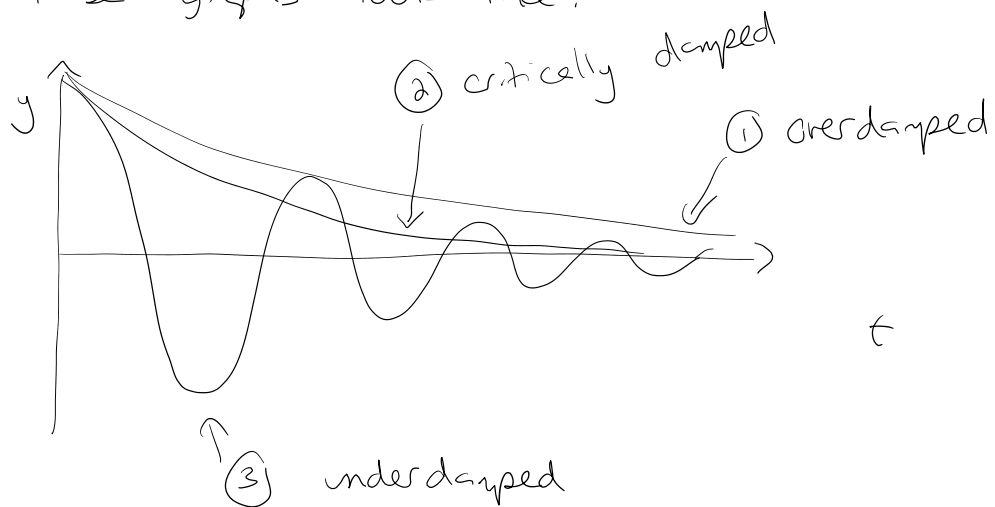
if " $\zeta < 0$

$$\text{with } y_1 = C_1 e^{n_1 t} + C_2 e^{n_2 t}$$

$$y_2 = (C_1 + C_2 t) e^{n t}$$

$$y_3 = e^{-\frac{b}{2m} t} (C_1 \cos \beta t + C_2 \sin \beta t)$$

so, what do these graphs look like?



critically damped - just enough friction to prevent oscillation

→ object returns to equilibrium in minimum time

what about an external force?

then get

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = F_{\text{ext}}(t)$$

example: buildings being pumped by a long-duration earthquake

example: Consider the situation in which a 1 kg mass is hung from a spring with spring constant 5 N/m. Air resistance is present with a damping constant numerically equal to 2. Initially, the mass is at rest in the equilibrium position. At $t=0$, an external force $F_{ext} = \cos t$ begins to act on the system.

Find $y(t)$ and identify any transient terms in the solution.

answer:

$$m \frac{d^2 y}{dt^2} + b \frac{dy}{dt} + ky = F_{ext}$$

$$1 \frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 5y = \cos t$$

y_c : aux eqn $n^2 + 2n + 5 = 0$ $n = -1 \pm 2i$

$$y_c = e^{nt} (c_1 \cos \beta t + c_2 \sin \beta t)$$

$$y_c = e^{-t} (c_1 \cos 2t + c_2 \sin 2t)$$

y_p : RHS = $\cos t$

$$y_p = A \cos t + B \sin t \quad \leftarrow \text{not bad case}$$

$$\frac{dy_p}{dt} = -A \sin t + B \cos t$$

$$\frac{d^2 y_p}{dt^2} = -A \cos t - B \sin t$$

now sub back into DE:

$$\frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 5y = \cos t$$

$$(-A \cos t - B \sin t) + 2(-A \sin t + B \cos t) + 5(A \cos t + B \sin t) = \cos t$$

$$(-A + 2B + 5A) \cos t + (-B - 2A + 5B) \sin t = \cos t$$

$$\left. \begin{aligned} 4A + 2B &= 1 \\ -2A + 4B &= 0 \end{aligned} \right\}$$

$$\begin{array}{r} 4A + 2B = 1 \\ -4A + 8B = 0 \\ \hline 10B = 1 \end{array}$$

$$B = \frac{1}{10}$$

$$\begin{aligned} -2A + 4B &= 0 \\ -2A + \frac{4}{10} &= 0 \end{aligned}$$

$$-2A = -\frac{4}{10}$$

$$A = \frac{1}{5}$$

$$\text{so } y_p = \frac{1}{5} \cos t + \frac{1}{10} \sin t$$

$$\begin{aligned} y &= y_c + y_p \\ &= e^{-t} (C_1 \cos 2t + C_2 \sin 2t) + \frac{1}{5} \cos t + \frac{1}{10} \sin t \end{aligned}$$

initial conditions: at $t=0$, $y=0$ ← start at equilib

$\frac{dy}{dt} = 0$ ← starts from rest

$$y=0 = C_1 + 0 + \frac{1}{5} + 0$$

$$\text{so } C_1 = -\frac{1}{5}$$

The second constant C_2 will be much more annoying due to product rule

$$y = e^{-t} (c_1 \cos 2t + c_2 \sin 2t) + \frac{1}{5} \cos t + \frac{1}{10} \sin t$$

$$\begin{aligned} \frac{dy}{dt} &= -e^{-t} (c_1 \cos 2t + c_2 \sin 2t) \\ &\quad + e^{-t} (-2c_1 \sin 2t + 2c_2 \cos 2t) \\ &\quad - \frac{1}{5} \sin t + \frac{1}{10} \cos t \end{aligned}$$

at $t=0$

$$0 = -(c_1 + 0) + (0 + 2c_2) + \frac{1}{10}$$

$$0 = -c_1 + c_2 + \frac{1}{10}$$

$$0 = \frac{1}{5} + 2c_2 + \frac{1}{10}$$

$$2c_2 = -\frac{3}{10}$$

$$c_2 = -\frac{3}{20}$$

$$y = e^{-t} \left(-\frac{1}{5} \cos 2t - \frac{3}{20} \sin 2t \right) + \frac{1}{5} \cos t + \frac{1}{10} \sin t$$

transient