

Section 7.1: Definition of the Laplace Transform

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Why do we care?

we can use the Laplace transform to reduce a linear DE to an algebraic eqn \leftarrow easy to solve

then do an inverse Laplace transform to the algebraic solution to get the solution to the DE

definition: for a function $f(t)$ which exists for $t \geq 0$

$$\mathcal{L}\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt$$

provided that the integral converges (so s has to be large enough to make this work)

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examples: Find the Laplace transform of $f(t) = 1$.

$$\begin{aligned} \text{answer: } \mathcal{L}\{1\} &= \int_0^{\infty} e^{-st} dt \\ &= \lim_{b \rightarrow \infty} \int_0^b e^{-st} dt \\ &= \lim_{b \rightarrow \infty} \left. \frac{e^{-st}}{-s} \right|_0^b \\ &= \lim_{b \rightarrow \infty} \left(\frac{e^{-sb}}{-s} - \frac{e^{-s \cdot 0}}{-s} \right) \end{aligned}$$

$$\begin{aligned}
 & b \rightarrow \infty \quad -s \quad 1_0 \\
 & = \lim_{b \rightarrow \infty} \left(\frac{-e^{-sb}}{s} + \frac{1}{s} \right) \\
 & = \frac{1}{s}
 \end{aligned}$$

similarly, $\mathcal{L}\{t\} = \frac{1}{s^2}$

$$\mathcal{L}\{e^{-3t}\} = \frac{1}{s+3}$$

for $s > -3$

need this condition for the limit to converge

now with Laplace transforms, we typically do not start from scratch with an integral, but rather consult a table:

$$\mathcal{L}\{1\} = \frac{1}{s}$$

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}} \quad \text{for } n = 1, 2, 3, \dots$$

$$\mathcal{L}\{e^{at}\} = \frac{1}{s-a} \quad (\text{assume } s > a)$$

so for example,

$$\mathcal{L}\{t^6\} = \frac{6!}{s^7}$$

note that all transforms are now functions of s , not t

nice property: Laplace transforms are linear

$$\text{if } f(t) = a g(t) + b h(t)$$

where a and b are constants

$$\text{then } \mathcal{L}\{f(t)\} = a \mathcal{L}\{g(t)\} + b \mathcal{L}\{h(t)\}$$

example: (1) $f(t) = t^2 - e^{2t} + 4$

$$\mathcal{L}\{f(t)\} = \frac{2}{s^3} - \frac{1}{s-2} + \frac{4}{s}$$

(2) $f(t) = \cos 3t + \sin 2t$

$$\mathcal{L}\{f(t)\} = \frac{s}{s^2+9} + \frac{2}{s^2+4}$$

notation:

$$\mathcal{L}\{f(t)\} = F(s)$$

function of t (pointing to $f(t)$)
function s (pointing to s)
lowercase f (pointing to f)
uppercase F (pointing to F)

$$\mathcal{L}\{g(t)\} = G(s)$$

$$\mathcal{L}\{y(t)\} = Y(s)$$

how do you deal with non-linear functions?

sometimes trig identities come in handy:

(1) if $f(t) = \cos^2 t$

$$\mathcal{L}\{f(t)\} = \mathcal{L}\left\{\frac{1 + \cos 2t}{2}\right\}$$

$$= \frac{1}{2s} + \frac{1}{2} \frac{s}{s^2+4}$$

(2) if $f(t) = \cos(\omega t + \phi)$, rewrite using sum/difference

$$\mathcal{L}\{f(t)\} = \mathcal{L}\left\{ \cos \omega t \overset{\text{constants}}{\cos \phi} - \sin \omega t \overset{\text{constants}}{\sin \phi} \right\}$$

$$= \cos \phi \frac{s}{s^2 + \omega^2} - \sin \phi \frac{\omega}{s^2 + \omega^2}$$

or sometimes you just do some algebra:

(3) if $f(t) = (2t-1)^3$

$$\mathcal{L}\{f(t)\} = \mathcal{L}\{8t^3 - 12t^2 + 6t - 1\}$$

$$= 8 \cdot \frac{3!}{s^4} - 12 \frac{2}{s^3} + \frac{6}{s^2} - \frac{1}{s}$$

note: (we do not test) the only place you use the definition is for piecewise functions

$$f(t) = \begin{cases} 2t+1 & 0 \leq t < 1 \\ 4 & t \geq 1 \end{cases}$$

$$\text{then } \mathcal{L}\{f(t)\} = \int_0^1 e^{-st} (2t+1) dt + \int_1^\infty e^{-st} 4 dt$$

etc

but how do they actually work?

suppose we have

$$\frac{dn}{dt} = -\lambda n \quad \text{with initial condition } n(0) \text{ is known}$$

to solve using Laplace, rewrite

$$\frac{dn}{dt} + \lambda n = 0$$

1st order linear
and separable

now take the Laplace transform of both sides

$$\mathcal{L}\left\{\frac{dn}{dt}\right\} + \lambda \mathcal{L}\{n\} = \mathcal{L}\{0\}$$



table says
 $\mathcal{L}\{f'(t)\} = sF(s) - f(0)$

$$sN(s) - n(0) + \lambda N(s) = 0$$

← this whole equation now contains no derivatives

DE → algebra

so solve for $N(s)$ algebraically

initial condition
↓

$$sN(s) + \lambda N(s) = n(0)$$

$$N(s) = \frac{n(0)}{s+\lambda}$$

now transform back

$$\begin{aligned} n(t) &= \mathcal{L}^{-1}\{N(s)\} \\ &= \mathcal{L}^{-1}\left\{\frac{n(0)}{s+\lambda}\right\} \end{aligned}$$

$$n(t) = n(\omega) e^{-i\omega t}$$

basic idea: Convert a system which is a function of time into a system which is a function of frequency

[Fourier: time \rightarrow modes of vibration]